CODING:

const int pingPin = 10; const int ledUS = 2; const int light = 7; const int pir = 4;

#define photoSensor A0 #define buzzer 3

int const PINO\_SGAS = A5; int const ledGas = 8;

int const button = 5; int const motor = 13;

void setup()

{

pinMode(ledUS, OUTPUT); pinMode(light, OUTPUT); pinMode(buzzer, OUTPUT); pinMode(ledGas, OUTPUT); pinMode(motor, OUTPUT); pinMode(pir, INPUT); pinMode(button, INPUT); pinMode(photoSensor, INPUT); Serial.begin(9600);

void loop()

{

long duration, cm;

int valLight = analogRead(photoSensor); int valPIR= digitalRead(pir);

int valGAS = analogRead(PINO\_SGAS); valGAS = map(valGAS, 300, 750, 0, 100);

int valBt = digitalRead(button); pinMode(pingPin, OUTPUT); digitalWrite(pingPin, LOW); delayMicroseconds(2); digitalWrite(pingPin, HIGH); delayMicroseconds(5); digitalWrite(pingPin, LOW);

pinMode(pingPin, INPUT); duration = pulseIn(pingPin, HIGH);

cm = microsecondsToCentimeters(duration);

if(cm < 336){ digitalWrite(ledUS, HIGH);

}else{

digitalWrite(ledUS, LOW);

}

if(valLight < 890){ digitalWrite(light, HIGH);

}else{

digitalWrite(light, LOW);

}

if(valPIR == 1){ digitalWrite(buzzer, HIGH);

}else{

digitalWrite(buzzer, LOW);

}

if(valBt == 1){ digitalWrite(motor, HIGH);

}else{

digitalWrite(motor, LOW);

}

if(valGAS > 20){ digitalWrite(ledGas, HIGH);

}else{

digitalWrite(ledGas, LOW);

Serial.print(valPIR); Serial.println();

}

long microsecondsToCentimeters(long microseconds) {

return microseconds / 29 / 2;

}

# CIRCUIT DIAGRAM :

